## AMENDMENTS TO THE CLAIMS

The following claim listing replaces all prior listings of the claims submitted in the application:

Claims 1 - 37. (Cancelled)

38. (Currently Amended) A fluid-handling device for ultrasonic manipulation of fluid-borne particles, comprising, in combination:

a fluid-handling manifold having a fluid inlet port and defining a fluid-handling void comprising at least a first fluid channel; and

an ultrasonic particle manipulator defining an ultrasonic cavity and comprising at least one ultrasonic transducer, the first fluid channel extending from the inlet port to the ultrasonic cavity and the ultrasonic particle manipulator being operative to establish an ultrasonic standing wave field in particle-bearing fluid in the first fluid channel at the ultrasonic cavity, and

wherein the ultrasonic cavity has a non-uniform configuration.

39. (Currently Amended) The fluid-handling device of <u>claim 91</u> <del>claim 38</del> for ultrasonic manipulation of fluid-borne particles, wherein the ultrasonic cavity has a non-uniform configuration.

Claims 40 - 42. (Cancelled)

43. (Currently Amended) The fluid-handling device of <u>claim 38 elaim 39</u> for ultrasonic manipulation of fluid-borne particles, wherein the ultrasonic cavity has a configuration that is non-uniform in the direction of flow.

## 44. - 55. (Cancelled)

- 56. (Currently Amended) The fluid-handling device of <u>claim 38 elaim 43</u> for ultrasonic manipulation of fluid-borne particles, wherein the ultrasonic cavity has a cross-sectional configuration that is non-uniform in a direction substantially transverse to the direction of flow in the first fluid channel.
- 57. (Currently Amended) The fluid-handling device of <u>claim 38 elaim 56</u> for ultrasonic manipulation of fluid-borne particles, wherein:

the fluid-handling void further comprises a second fluid channel in fluid communication with the first fluid channel at an intersection within the ultrasonic cavity:

the ultrasonic transducer particle manipulator is operative to establish an ultrasonic standing wave field fields having an axial direction of standing wave propagation substantially perpendicular to the direction of fluid communication through the intersection;

the cross-sectional configuration of the ultrasonic cavity is non-uniform in the direction of fluid communication through the intersection; and

the ultrasonic particle manipulator is operative to collect fluid-borne particles from fluid in the first fluid channel and move collected fluid-borne particles through the

intersection to the second fluid channel by varying the actuation frequency of the ultrasonic transducer.

- 58. (Original) The fluid-handling device of claim 57 for ultrasonic manipulation of fluid-borne particles, wherein the ultrasonic particle manipulator is operative to selectively position an ultrasonic standing wave field in the second fluid channel.
- 59. (Original) The fluid-handling device of claim 57 for ultrasonic manipulation of fluid-borne particles, wherein the ultrasonic particle manipulator is operative to selectively position an ultrasonic standing wave field in the intersection of the first and second fluid channels.
- 60. (Original) The fluid-handling device of claim 57 for ultrasonic manipulation of fluid-borne particles, wherein the dimension of the ultrasonic cavity in the axial direction of standing wave propagation increases stepwise along the direction of fluid communication through the intersection.
- 61. (Original) The fluid-handling device of claim 57 for ultrasonic manipulation of fluid-borne particles, wherein the dimension of the ultrasonic cavity in the axial direction of standing wave propagation increases continuously along the direction of fluid communication through the intersection.

- 62. (Original) The fluid-handling device of claim 57 for ultrasonic manipulation of fluid-borne particles, wherein the dimension of the ultrasonic cavity in the axial direction of standing wave propagation varies wave-like along the direction of fluid communication through the intersection.
- 63. (Original) The fluid-handling device of claim 57 for ultrasonic manipulation of fluid-borne particles, wherein a surface of the ultrasonic cavity is formed by the ultrasonic transducer and has a stepwise configuration along the direction of fluid communication through the intersection.
- 64. (Original) The fluid-handling device of claim 57 for ultrasonic manipulation of fluid-borne particles, wherein a surface of the ultrasonic cavity is formed by the ultrasonic transducer and has a sloping configuration along the direction of fluid communication through the intersection.
- 65. (Original) The fluid-handling device of claim 57 for ultrasonic manipulation of fluid-borne particles, wherein a surface of the ultrasonic cavity is formed by the ultrasonic transducer and has a wave-like configuration along the direction of fluid communication through the intersection.
- 66. (Original) The fluid-handling device of claim 57 for ultrasonic manipulation of fluid-borne particles, wherein a surface of the ultrasonic cavity is formed by an

ultrasonic reflector and has a stepwise configuration along the direction of fluid communication through the intersection.

- 67. (Original) The fluid-handling device of claim 57 for ultrasonic manipulation of fluid-borne particles, wherein a surface of the ultrasonic cavity is formed by an ultrasonic reflector and has a sloping configuration along the direction of fluid communication through the intersection.
- 68. (Original) The fluid-handling device of claim 57 for ultrasonic manipulation of fluid-borne particles, wherein a surface of the ultrasonic cavity is formed by the ultrasonic reflector and has a wave-like configuration along the direction of fluid communication through the intersection.
- 69. (Currently Amended) The fluid-handling device of <u>claim 38 elaim 57</u> for ultrasonic manipulation of fluid-borne particles, <u>further comprising a second fluid channel in fluid communication with the first fluid channel at an intersection within the ultrasonic cavity</u>, wherein the first fluid <del>flow</del> channel and the second fluid <del>flow</del> channel extend substantially parallel each other on opposite sides of a dividing wall between them, and <u>wherein</u> the intersection comprises a passageway through the dividing wall.
- 70. (Currently Amended) The fluid-handling device of claim 69 for ultrasonic manipulation of fluid-borne particles, wherein the dividing wall between the first and second fluid flow channels is 10 microns [[:m]] to 30 microns [[:m]] thick.

- 71. (Currently Amended) The fluid-handling device of claim 57 for ultrasonic manipulation of fluid-borne particles, wherein the first fluid <del>flow</del> channel and the second fluid <del>flow</del> channel intersect each other substantially tangentially.
- 72. (Currently Amended) The fluid-handling device of claim 57 for ultrasonic manipulation of fluid-borne particles, wherein the intersection between the first fluid flow channel and the second fluid flow channel comprises an [[a]] orifice.

Claims 73 - 84. (Cancelled)

- 85. (Currently Amended) An omni-directional A fluid-handling device for ultrasonic manipulation of fluid-borne particles, comprising, in combination:
- a fluid-handling manifold having a fluid inlet port; and defining a fluid-handling void comprising at least

a first fluid channel in fluid communication with the fluid inlet port; and an omni-directional ultrasonic particle manipulator comprising at least one ultrasonic transducer and an acoustic reflector positioned opposite the ultrasonic transducer, the ultrasonic transducer and the acoustic reflector cooperatively defining between them an ultrasonic cavity and operative in any orientation relative to gravity to separate fluid-borne particles from fluid flowed through the ultrasonic cavity by establishing an ultrasonic standing wave field in a portion of the first fluid channel

extending through the ultrasonic cavity, wherein the spacing between the ultrasonic

transducer and the acoustic reflector is not more than 300 microns; and

a second fluid channel in fluid communication with the first fluid channel at an

intersection within the ultrasonic cavity;

wherein the first fluid channel and the second fluid channel extend substantially

parallel each other on opposite sides of a dividing wall between them, and

wherein the intersection comprises a passageway through the dividing wall.

86. (Cancelled)

87. (New) The fluid-handling device of claim 85 for ultrasonic manipulation of fluid-

borne particles, wherein the spacing between the ultrasonic transducer and the acoustic

reflector is not more than 300 microns.

88. (New) The fluid-handling device of claim 85 for ultrasonic manipulation of fluid-

borne particles, wherein the ultrasonic particle manipulator is operative to establish an

ultrasonic standing wave field having an axial direction of standing wave propagation

substantially perpendicular to the direction of fluid communication through the

intersection.

89. (New) The fluid-handling device of claim 85 for ultrasonic manipulation of fluid-

borne particles, wherein the cross-sectional configuration of the ultrasonic cavity is non-

uniform in the direction of fluid communication through the intersection.

- 90. (New) The fluid-handling device of claim 85 for ultrasonic manipulation of fluid-borne particles, wherein the ultrasonic particle manipulator is operative to collect fluid-borne particles from fluid in the first fluid channel and move collected fluid-borne particles through the intersection to the second fluid channel by varying the actuation frequency of the ultrasonic transducer.
- 91. (New) A fluid-handling device for ultrasonic manipulation of fluid-borne particles, comprising:

an ultrasonic particle manipulator defining an ultrasonic cavity and comprising at least one ultrasonic transducer;

a first fluid channel extending into the ultrasonic cavity;

a second fluid channel in fluid communication with the first fluid channel at an intersection within the ultrasonic cavity;

wherein the first fluid channel and the second fluid channel extend substantially parallel each other on opposite sides of a dividing wall between them, and the intersection comprises a passageway through the dividing wall, and

wherein the ultrasonic particle manipulator is operative to establish an ultrasonic standing wave field in fluid in the ultrasonic cavity.

92. (New) The fluid-handling device of claim 91 for ultrasonic manipulation of fluidborne particles, wherein the ultrasonic particle manipulator is operative to establish an ultrasonic standing wave field having an axial direction of standing wave propagation substantially perpendicular to the direction of fluid communication through the

intersection.

93. (New) The fluid-handling device of claim 91 for ultrasonic manipulation of fluid-

borne particles, wherein the cross-sectional configuration of the ultrasonic cavity is non-

uniform in the direction of fluid communication through the intersection.

94. (New) The fluid-handling device of claim 91 for ultrasonic manipulation of fluid-

borne particles, wherein the ultrasonic particle manipulator is operative to collect fluid-

borne particles from fluid in the first fluid channel and move collected fluid-borne

particles through the intersection to the second fluid channel by varying the actuation

frequency of the ultrasonic transducer.

95. (New) The fluid-handling device of claim 91 for ultrasonic manipulation of fluid-

borne particles, wherein the dimension of the ultrasonic cavity in the axial direction of

standing wave propagation increases stepwise along the direction of fluid communication

through the intersection.

96. (New) The fluid-handling device of claim 91 for ultrasonic manipulation of fluid-

borne particles, wherein the spacing between the ultrasonic transducer and the acoustic

reflector is not more than 300 microns.